

GPIO on the Raspberry Pi

JOSH SANZ

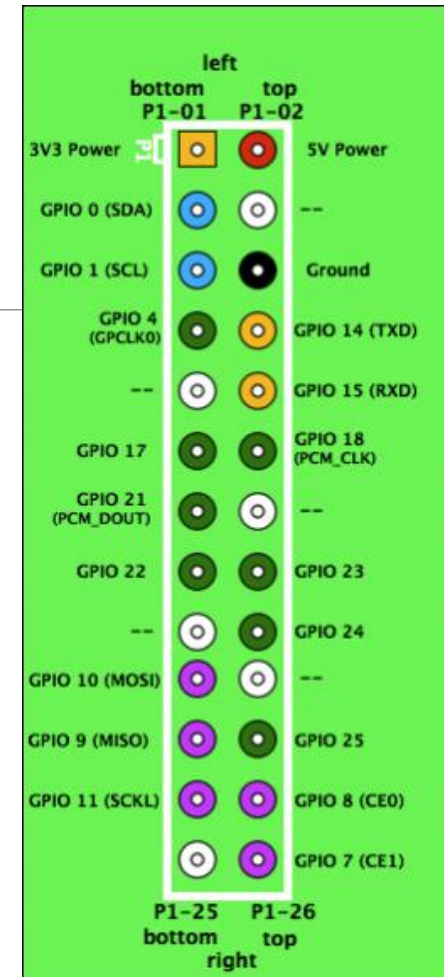


General Purpose Input/Output

- No dedicated purpose
- Programmable
- Commonly found on multipurpose platforms
- Often grouped as ports

Raspberry Pi Model B

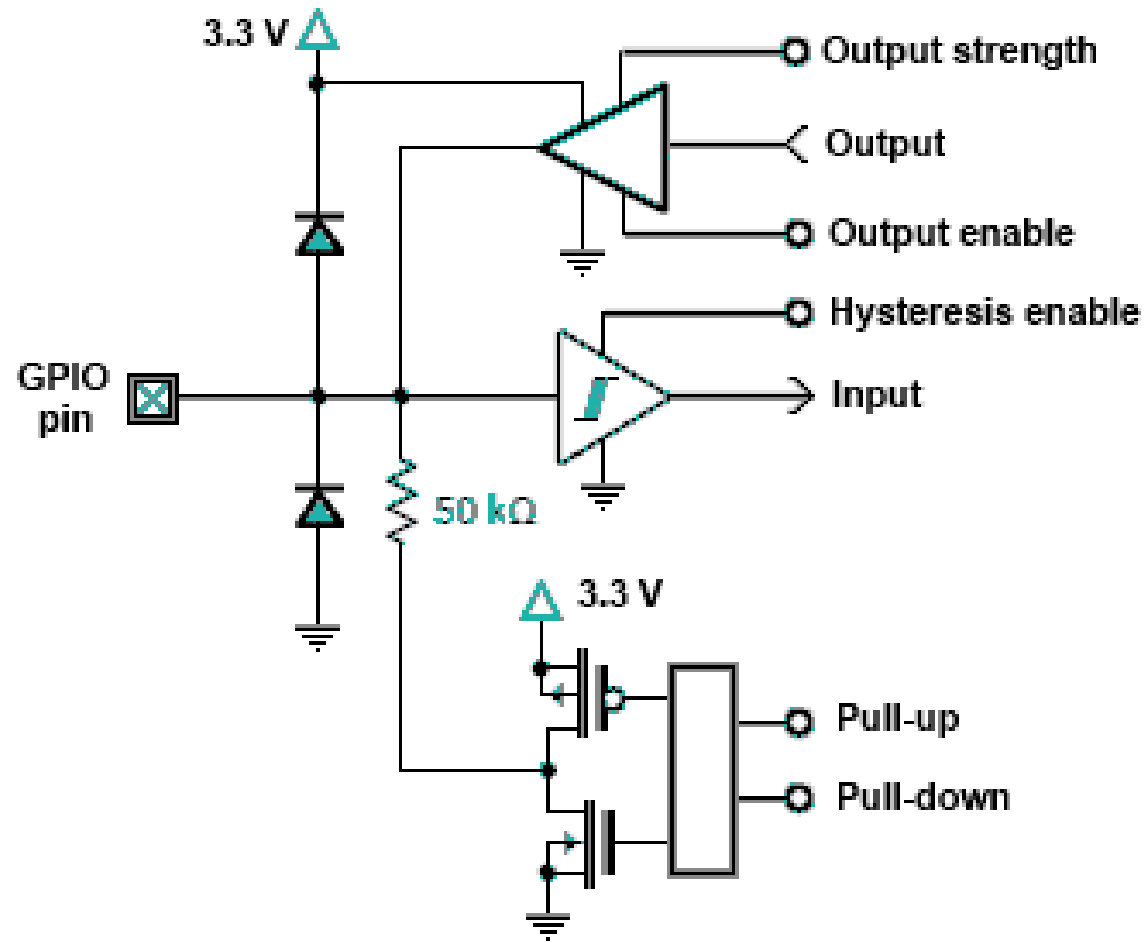
- 26 pins
 - 17 actually GPIO
- 3.3 V
- 16 mA
- Configurable pull-up/pull-down
- Configurable purpose
 - I2C
 - UART
 - SPI



[source](#)

For electrical characteristics: <http://www.mosaic-industries.com/embedded-systems/microcontroller-projects/raspberry-pi/gpio-pin-electrical-specifications>

Equivalent Circuit for Raspberry Pi GPIO pins



Circuit Diagram for RPi GPIO pins

Controlling the Pins

With Bash

- First export the pin
 - `echo "4" > /sys/class/gpio/export`
- Then set input/output
 - `echo "out" > /sys/class/gpio/gpio4/direction`
- Read/write
 - `echo "1" > /sys/class/gpio/gpio4/value`
 - `cat /sys/class/gpio/gpio4/value`
- Clean up
 - `echo "4" > /sys/class/gpio/unexport`

With C

- Use [this library](#)
- Example code

```
#include <bcm2835.h>
// Blinks on RPi pin GPIO 11
#define PIN RPI_GPIO_P1_11
void main()
{
    // Set the pin to be an output
    bcm2835_gpio_fsel(PIN, BCM2835_GPIO_FSEL_OUTP);
    // Blink
    while (1)
    {
        // Turn it on
        bcm2835_gpio_write(PIN, HIGH);
        // wait a bit
        delay(500);
        // turn it off
        bcm2835_gpio_write(PIN, LOW);
    }
}
```

With Python!!!

- Use RPi.GPIO
 - Included in Raspbian
- Great for:
 - I/O
 - PWM
 - Edge detection
 - Interrupts
 - Software debounce

```
# sample RPi GPIO code
import RPi.GPIO as GPIO
import sleep

GPIO.setmode(GPIO.BOARD)
GPIO.setup(24, GPIO.IN) # sets CE0/pin24 to input

if GPIO.input(24):
    print "Pin 24 is HIGH"
else:
    print "Pin 24 is LOW"

GPIO.cleanup() # return all channels to input w/out pull up or down
```

Here are some easy to follow examples: <http://sourceforge.net/p/raspberry-gpio-python/wiki/Examples/>

With Other Languages?

- Perl
- Ruby
- Java
- BASIC
- Etc...

Everything you might want is here: [http://elinux.org/RPi_Low-level_peripherals#General Purpose Input.2FOutput .28GPIO.29](http://elinux.org/RPi_Low-level_peripherals#General_Purpose_Input.2FOutput_.28GPIO.29)

Applications

- Peripheral sensors
 - Must communicate digitally, no analog
- Control motors
- Control external displays



Questions?
